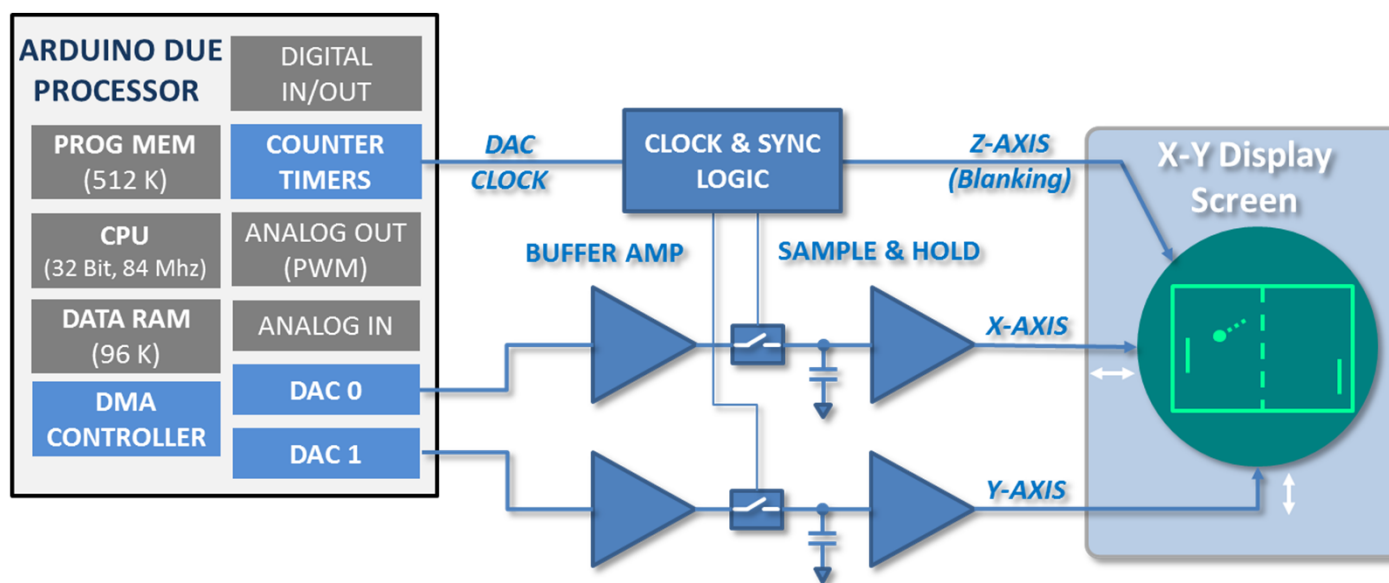


TABLE OF CONTENTS

Table of Contents	1
AGI Block Diagram	2
An Oscilloscope Overview	3
Parts List – AGI Project.....	4
AGI Oscilloscope Requirements.....	5
Parts List – AGI PCB ASSEMBLY.....	6
AGI PCB Schematic.....	7
Bare Printed Circuit Board – Rev 0	8
Load Parts: .1uf Capacitor, 1N4004 Diode	9
Load Parts: 470pf, 47uf, 330uf Capacitor	10
Load Parts: Resistors	11
Load Parts: 10K Resistors, Q1, Q2, SW1	12
Power Switch Wiring.....	13
Load Parts: Potentiometers & Test Points	14
Load Parts: Headers, Connectors, ICs	15
Power Supply Checks & IC Installation	16
Test Mode Mounting, DUE to AGI PCB	17
Final Mounting of DUE to AGI PCB	18
Wiring AGI To DUE	19
X-Axis Gain and Offset Adjust.....	20
Y-Axis Gain and Offset Adjust.....	21
Blanking Select & Wiring AGI To Scope	22
Test Pattern Descriptions	23

AGI Block Diagram



Parts List – AGI Project

Item	Ref Designators	QTY	Description/Values/Notes	Manufacturer	Mfg PN	Alternate Sources	Additional Notes
1	AGI PCB Assembly	1	--	--	--	--	See build PCB Documentation beginning on page 6.
2	Arduino Due Processor Board	1	ARDUINO DUE (or compatible)	Arduino.org	See Web Site	Amazon, eBay, & others	
3	BNC to BNC Cables	2	BNC to BNC, 50Ohm Cable, 3-5Ft Length, AGI to Oscilloscope Interconnect	Various	Various	Amazon, eBay, & others	Shielded or Twisted Pair cabling is recommended; Final method & length of XYZ interconnection is BUILDER'S choice
4	+ 12VDC Power Supply	1	+12 VDC @ 2 Amp	Various	Various	Amazon, eBay, & others	Selection of Power Supply and method of interconnect to AGI PCB is BUILDER'S choice
5	Hookup Wire	AR	Wire for interconnection between AGI and Arduino Due	Various, As Required	Various	Amazon, eBay, & others	Method of interconnection is BUILDER'S choice
5	Misc Headers to facilitate interconnect	AR	Connectors headers for interconnect between AGI and Due	Various, As Required	Various	Amazon, eBay, & others	Method of interconnection is BUILDERS choice
6	4-40 X 0.75 In Long Spacer (Spacer, Nuts, Screws AR)	4	Spacers used to mount DUE to TOP OF AGI PCB	Various	Various	Amazon, eBay, & others	Final mounting method is BUILDER'S choice
7	4-40 X 0.75 In Long Spacer (Spacer, Nuts, Screws AR)	4	Spacers used to mount AGI to a base or enclosure	Various	Various	Amazon, eBay, & others	Final mounting method is BUILDER'S choice
8	Project Enclosure	1	As Required, BUILDER'S choice	Various	Various	Amazon, eBay, & others	Final enclosure method is BUILDER's choice
9	Analog Oscilloscope with XYZ Drive Capability	1	Analog Oscilloscope is required as the final display device. Note: DIGITAL scopes will not work.	Various	Various	Amazon, eBay, & others	See OSCILLOSCOPE REQUIREMENTS page to qualify possible oscilloscope candidates.

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3

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An Oscilloscope Overview

An Analog Oscilloscope Overview

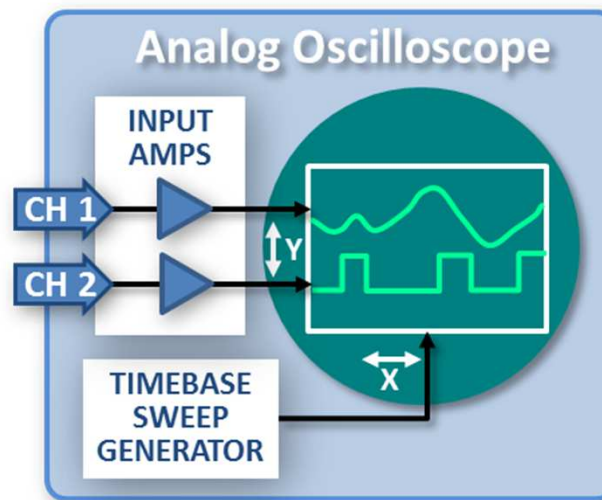
An oscilloscope accepts a voltage input from a device under test and displays that voltage as a dot on a display screen. A positive voltage into the scope drives the Y-axis of the trace, moving the 'dot' up on the screen, while a negative voltage input moves the 'dot' down. A second, independent voltage is applied to the X-axis of the oscilloscope. In this case, a positive voltage moves the dot to the right along the X-axis while a negative voltage moves the dot to the left.

By applying the unknown test voltage into the Y-axis and a linear ramp waveform into the X-axis, the dot will graphically show how the unknown test voltage changes over time.

The linear ramp waveform driving the X-axis waveform is created inside the oscilloscope by an internal time base sweep generator circuit. Two (or four) channel oscilloscopes allow multiple signals to be simultaneously traced across the screen. With careful calibration of the time base and input amplifiers of the scope, precise amplitude and time measurements are made.

The earliest computer graphics and radar displays (circa: 1940-1970's) used CRTs driven in an X-Y fashion to show monochrome vector graphic displays.

This project side steps the internal Time Base sweep generator of the oscilloscope and drives by the X & Y axis with a microprocessor. In this way we can show high resolution vector art graphic images on an oscilloscope screen.



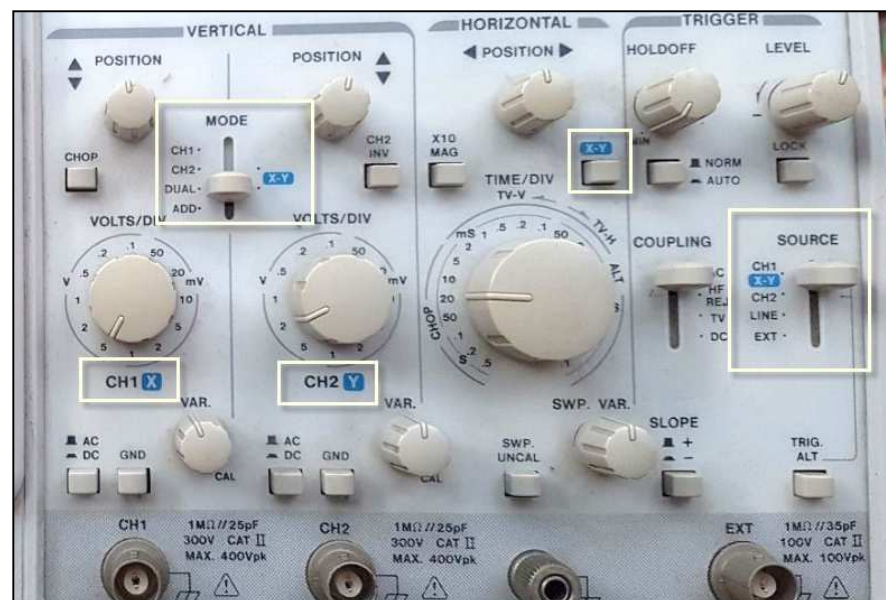
AGI Oscilloscope Requirements

Overall graphics quality is influenced by the quality and performance of the oscilloscope and CRT used. This project works well only with ANALOG Oscilloscopes; Digital scopes will only produce poor looking output.

There are many analog scopes manufactured by Tektronix, HP, Phillips, Leader, GW-Instek and others that will work well. Look for these key features to find a suitable scope for this project:

- Screen size: Larger is better!
- Scope must support an X-Y Mode
- Scope must be run in DC Mode

Typical Scope Front Panel View
showing XY Operation Controls



Typical Scope Rear Panel View
showing Z-AXIS INPUT connector



Parts List – AGI PCB ASSEMBLY

NOTE: Use PCB or hand-wire using Prototype Perf-Board for assembly. Use of IC sockets for all 8-pin and 14-pin devices is recommended.

Item	Ref Designators	QTY	Value/Notes	Manufacturer	Mfg PN	Digikey (DK) PN	Description & Add'l Data
1	C10,C12	2	470pf	KEMET	C410C471J1G5TA7200	DK: 399-4473-1-ND	CAP CER 470PF 100V COG/NPO AXIAL
2	C11,C13,C14,C15,C16,C4,C5,C8,C9	9	.1uf	Taiyo Yuden	UP050F104Z-A-BZ	DK: 587-5501-1-ND	CAP CER 0.1UF 50V AXIAL
3	C2,C7	2	330uf	Panasonic	ECA-1EHG331	DK: P5542-ND	CAP ALUM 330UF 20% 25V RADIAL
4	C3,C6	2	47uf	Panasonic	EEU-FC1H470	DK: P10321-ND	CAP ALUM 47UF 20% 50V RADIAL
5	D1	1	1N4004	Micro Com	1N4004-TP	DK: 1N4004-TPMSCT-ND	DIODE GEN PURP 400V 1A DO41
6	L1,L2	2	LED 3MM GRN	Broadcom Limited	HLMP-1503-C0002	DK: 516-3190-2-ND	LED GRN DIFF 3MM ROUND T/H
7	P1,P2,P3	3	Can use Chassis Mount BNC	TE Connectivity AMP Connectors	1-1634612-0	DK: A97555-ND	CONN BNC JACK R/A 50 OHM PCB
8	PL1	1	Alt: Jumper Wire	Samtec	MALE: TSW-110-07-T-S FEMALE: SSA-110-S-T	MALE DK: SAM1035-10-ND FEMALE DK: SAM1035-10-ND	10 PIN .025" SQ. MALE OR FEMALE TERM
9	PL2	1	Alt: Jumper Wire	Samtec	HTSW-101-07-T-S	DK: SAM11363-ND	4 PIN .025" SQ. MALE TERM
10	PL3	1	Alt: Jumper Wire	Samtec	MALE: TSW-108-07-T-S FEMALE: SSA-108-S-T	MALE DK: SAM1035-08-ND FEMALE: SAM1122-08-ND	8 PIN .025" SQ. MALE OR FEMALE TERM
11	PL4	1	Alt: Jumper Wire	Samtec	MALE: HTSW-101-07-T-S	MALE DK: SAM11363-ND	4 PIN .025" SQ. MALE OR FEMALE TERM
12	PL5	1	Alt: Jumper Wire	Samtec	MALE: TSW-102-24-T-S FEMALE: SSA-102-S-T	MALE DK: SAM12303-ND FEMALE DK: SAM1122-02-ND	2 PIN .025" SQ. MALE OR FEMALE TERM
13	PL6	1	Alt: Jumper Wire	Samtec	TSW-103-15-T-S	DK: SAM9525-ND	3 PIN .025" SQ. MALE TERM
14	Q1,Q2	2	IRFD9120	Vishay, Siliconix	IRFD9120PBF	DK: IRFD9120PBF-ND	MOSFET P-CH 100V 1A 4-DIP
15	R1,R11,R4,R8	4	4.7K	Yageo	CFR-25JB-52-4K7	DK: 4.7KQBK-ND	RES 4.7K OHM 1/4W 5% AXIAL
16	R10,R13	2	10K	Bourns, Inc	PV36W103C01B00	DK: 490-2875-ND	TRIMMER 10K OHM 0.5W TH
17	R12,R2,R3,R5	4	10K	Yageo	MFR-25BFB52-10K	DK: 10.0KXBK-ND	RES 10K OHM 1/4W 1% AXIAL
18	R14,R6	2	100K	Bourns, Inc	PV36W104C01B00	DK: 490-2876-ND	TRIMMER 100K OHM 0.5W TH
19	R15,R16	2	1K	Yageo	MFR-25BFB52-1K	DK: 1.00KXBK-ND	RES 1K OHM 1/4W 1% AXIAL
20	R7	1	220	Yageo	CFR-25JB-52-220R	DK: 220QBK-ND	RES 220 OHM 1/4W 5% AXIAL
21	R9	1	1.5K	Yageo	MFR-25BFB52-1K5	DK: 1.50KXBK-ND	RES 1.5K OHM 1/4W 1% AXIAL
22	SW1	1	1 A @ 20 VDC	BUILDER CHOICE	BUILDER CHOICE	BUILDER CHOICE	PWR SWITCH for remote mount as desired. Substitute jumper wire if not needed (See Build Doc for details)
23	TP1,TP10,TP11,TP12,TP13,TP14,TP15,TP16,TP17,TP18,TP2,TP3,TP4,TP5,TP6,TP7,TP8,TP9	18	OPTIONAL	Samtec	HTSW-101-07-T-S	DK: SAM11363-ND	1 PIN .025" SQ. MALE TERM OR HAND-FORM TEST POINT FROM INSULATED, SOLID-CORE WIRE. PHYSICAL TEST POINTS ARE NOT REQUIRED AND MAY BE OMITTED IF DESIRED .
24	U1	1	LM317	Fairchild/ON Semi	LM317AHVT	DK: LM317AHVT-ND	IC REG LINEAR ADJ 1A TO220-3 [Heat Sink Required!]
25	U2	1	LM7805	Fairchild/ON Semi	LM7805ACT	DK: LM7805ACT-ND	IC REG LDO 5V 1A TO220-3 [Heat Sink Required!]
26	U3,U4	2	CA3240	Intersil	CA3240EZ	DK: CA3240EZ-ND	IC OPAMP GP 4.5MHZ 8DIP (USE 8-PIN SOCKET)
27	U5	1	CD4066	Texas Inst.	CD4066BE	DK: 296-2061-5-ND	QUAD BILATERAL SWITCH 14-DIP (USE 14-PIN SOCKET)
28	U6	1	CD1013BE	Texas Inst.	CD4013BE	DK: 296-2033-5-ND	IC D-TYPE POS TRG DUAL 14DIP (USE 14-PIN SOCKET)
29	U7	1	74HC00	Tex Instr.	74HC00E	DK: 296-12769-5-ND	IC GATE NAND 4CH 2-INP 14-DIP (USE 14-PIN SOCKET)
30	U8	1	74LS14	Tex Instr.	SN74LS14N	DK: 296-1643-5-ND	IC HEX SCHMITT-TRIG INV 14-DIP (USE 14-PIN SOCKET)

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AGI: Arduino Graphics Interface

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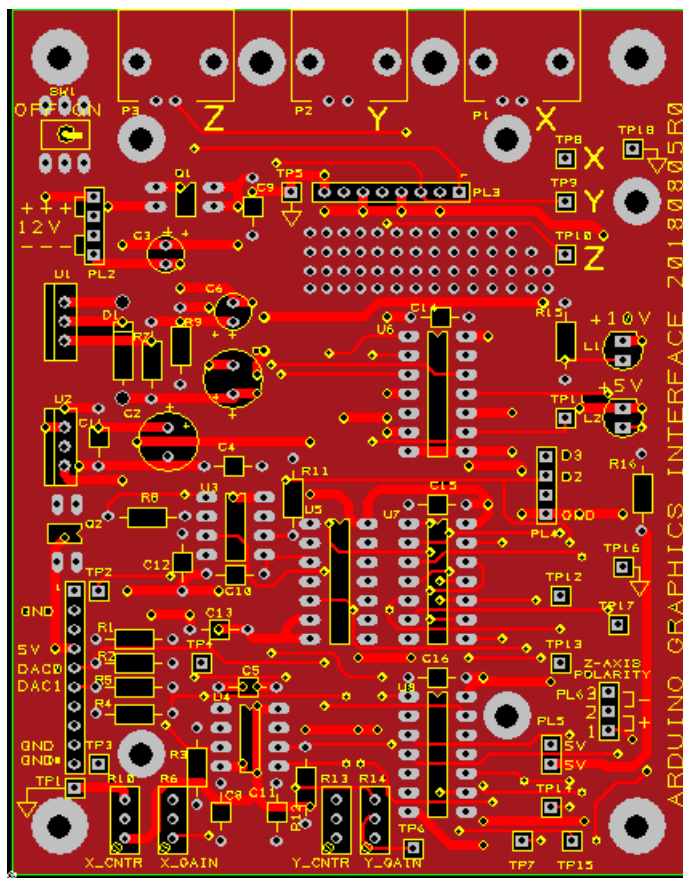
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6

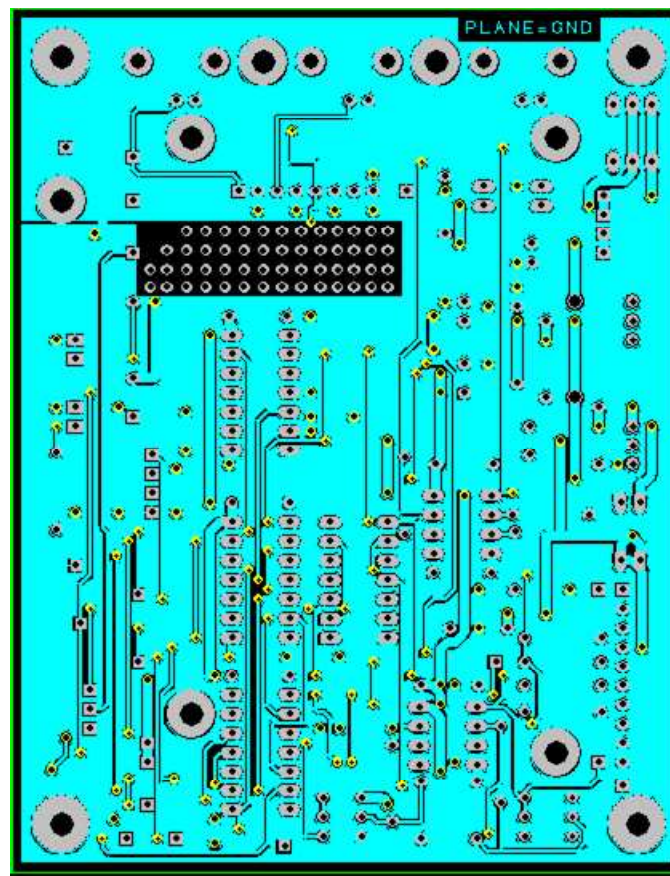
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Bare Printed Circuit Board – Rev 0

TOP SIDE
VIEW



BOTTOM
SIDE
VIEW



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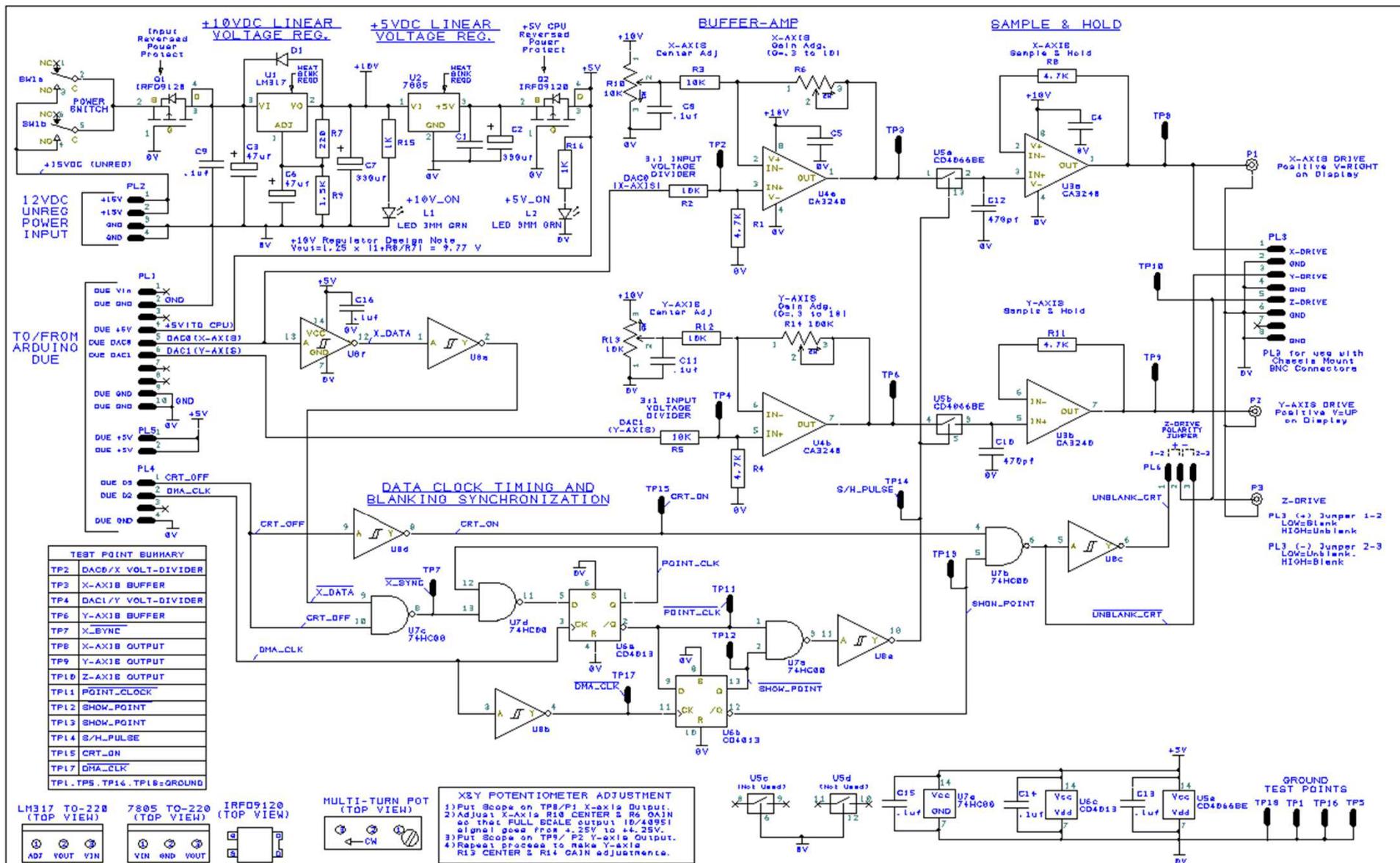
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7

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Drn	Drn	Drn	Drn	Project AGI GRAPHICS INTER'FC			Client N&V Article		E. ANDREWS 8-4-2017	
									AMC Consulting Brookfield, WI 53045	
Chk	Chk	Chk	Chk	Title 20180805R0 (SCHEMATIC)			Filename X-Y Graphics Intfc (Rev_0).sch		Drawing No. X-Y Graphics Intfc (Rev_0).sch X-Y Graphics Intfc (Rev_0).pcb	Sheet 1 of 1

Load Parts: .1uf Capacitor, 1N4004 Diode

TOP SIDE VIEW

BEFORE YOU BEGIN ASSEMBLY

Use and OHM METER to verify the following:

1. +5V bus is NOT SHORTED TO GROUND.
2. +10V bus is NOT SHORTED TO GROUND.
3. +5V bus is NOT SHORTED to +10V bus.
4. +12 V input is NOT SHORTED TO +10V.

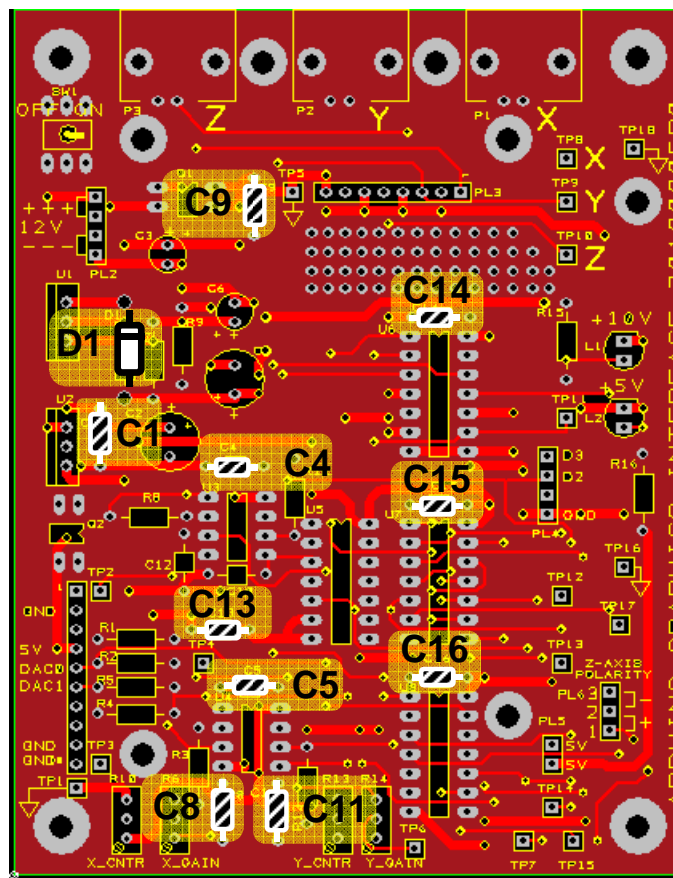
Ref Name	Qty	Value
C1	1	.1uf
C11	1	.1uf
C13	1	.1uf
C14	1	.1uf
C15	1	.1uf
C16	1	.1uf
C4	1	.1uf
C5	1	.1uf
C8	1	.1uf
C9	1	.1uf



D1	1	1N4004
----	---	--------



←Observe Polarity!



Load Parts: 470pf, 47uf, 330uf Capacitor

Ref Name	Qty	Value
C10	1	470pf
C12	1	470pf



C3	1	47uf
C6	1	47uf



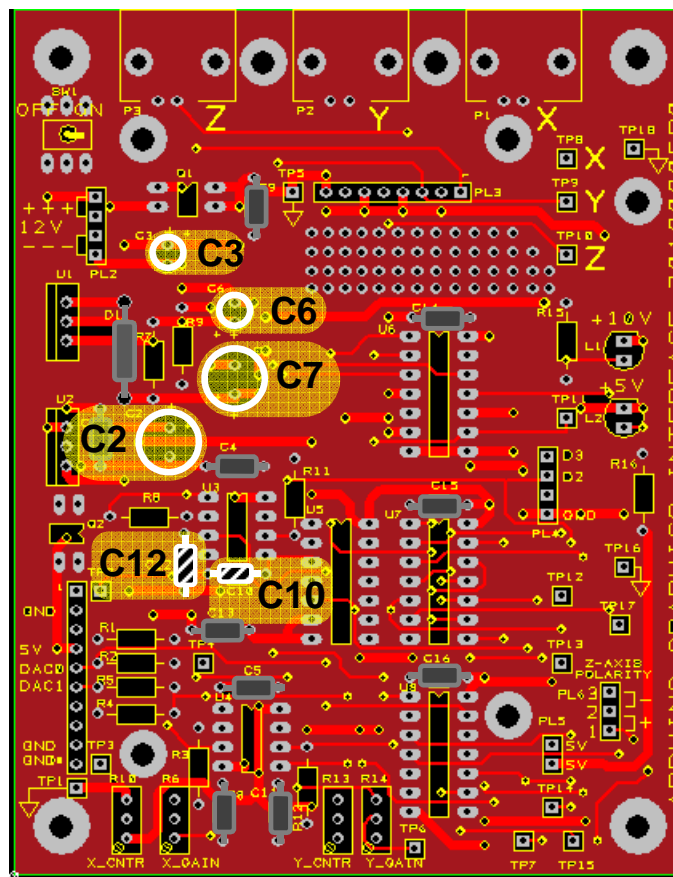
←Observe
Polarity!

C2	1	330uf
C7	1	330uf



←Observe
Polarity!

TOP SIDE VIEW



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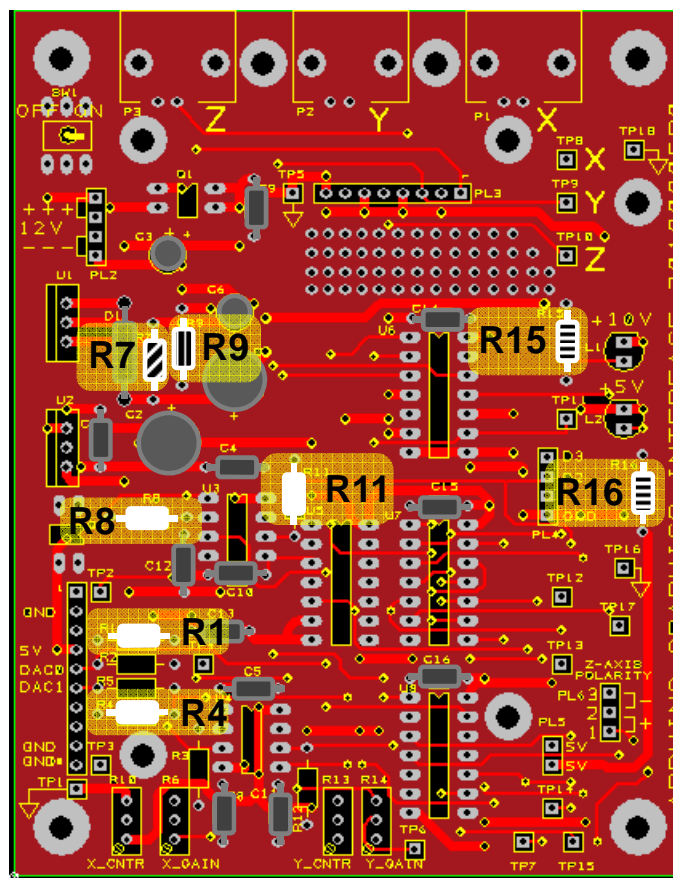
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Load Parts: Resistors

Ref Name	Qty	Value
R7	1	220 
R9	1	1.5K 
R15	1	1K 
R16	1	1K 
R1	1	4.7K 
R11	1	4.7K 
R4	1	4.7K 
R8	1	4.7K 

TOP SIDE VIEW



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Page

11

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Load Parts: 10K Resistors, Q1, Q2, SW1

TOP SIDE VIEW

Ref Name	Qty	Value
R12	1	10K
R2	1	10K
R3	1	10K
R5	1	10K



Q1	1	IRFD9120
Q2	1	IRFD9120



←Note device orientation!

U1	1	LM317
----	---	-------

←Note device orientation!

U2	1	LM7805
----	---	--------

←Note device orientation!

Note:

- 1) **WARNING:** Heat Sink Tab on U1 LM317 = +9.8 VDC.
- 2) **WARNING:** Heat Sink Tab on U2 LM7805 = GND.

DO NOT MOUNT U1 Heat Sink to GROUND. DO NOT mount U1 & U2 to a COMMON Heat sink unless insulating washers & hardware are used to electrically insulate tabs from one another and heat sink base metal!

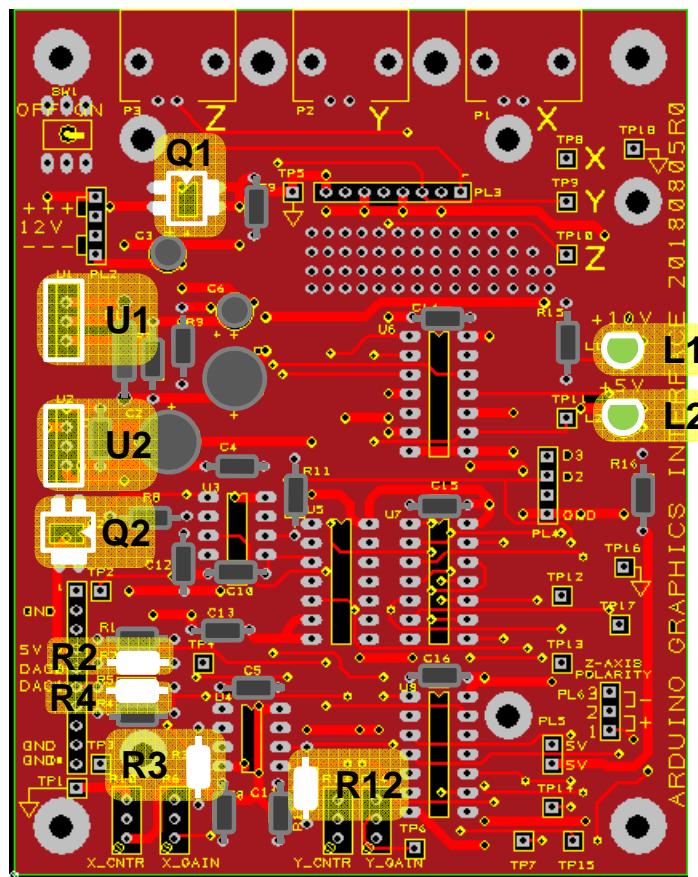
- 3) To ensure proper spacing & placement, Mount **U1** and **U2** devices to heatsink(s) **BEFORE** installing and attaching to PCB!

Ref Name	Qty	Value
L1	1	LED 3MM GRN
L2	1	LED 3MM GRN



←Note device orientation!

Note: Builders Choice - Any color LED may be used.

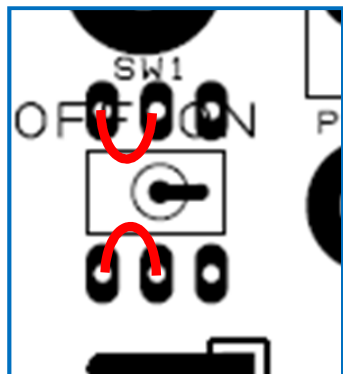


Power Switch Wiring

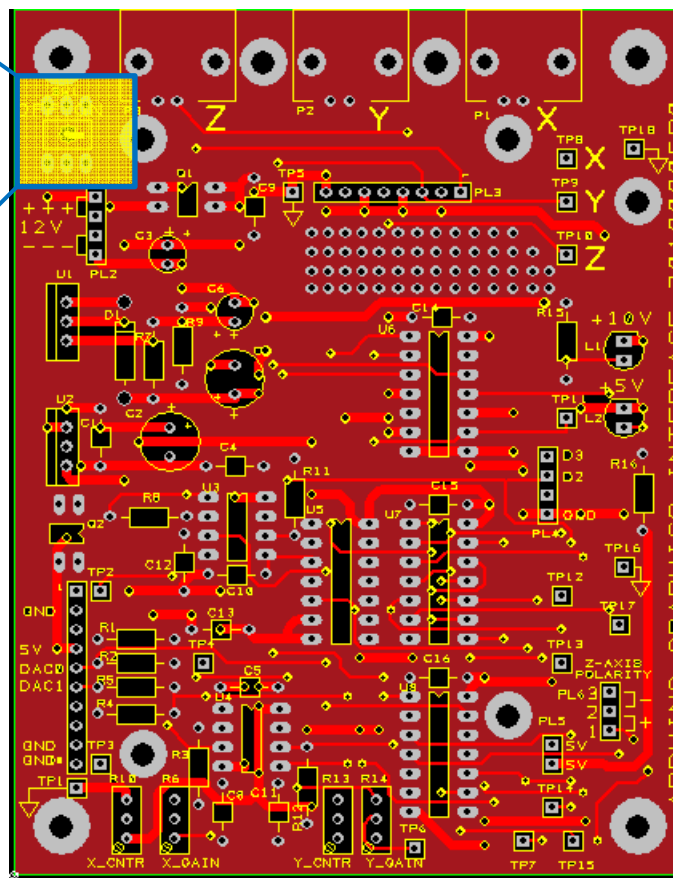
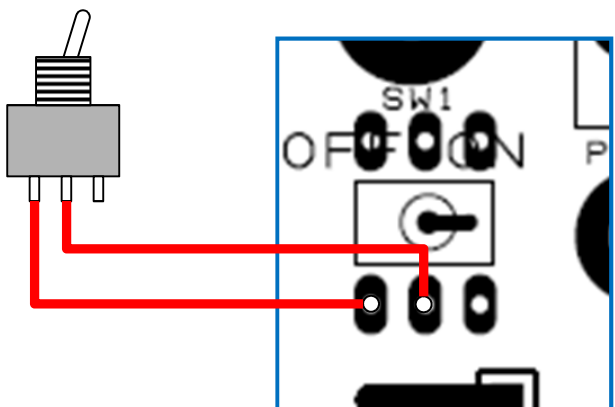
TOP SIDE VIEW

OPTION 1: NO EXTERNAL POWER SWITCH

If no external power switch is desired, install jumper wires as shown.



OPTION 2: OFF BOARD POWER SWITCH



Load Parts: Potentiometers & Test Points

Ref Name	Qty	Value
R10	1	10K 10 Turn Potentiometer
R13	1	10K 10 Turn Potentiometer
R14	1	100K 10 Turn Potentiometer
R6	1	100K 10 Turn Potentiometer

←Note device orientation!

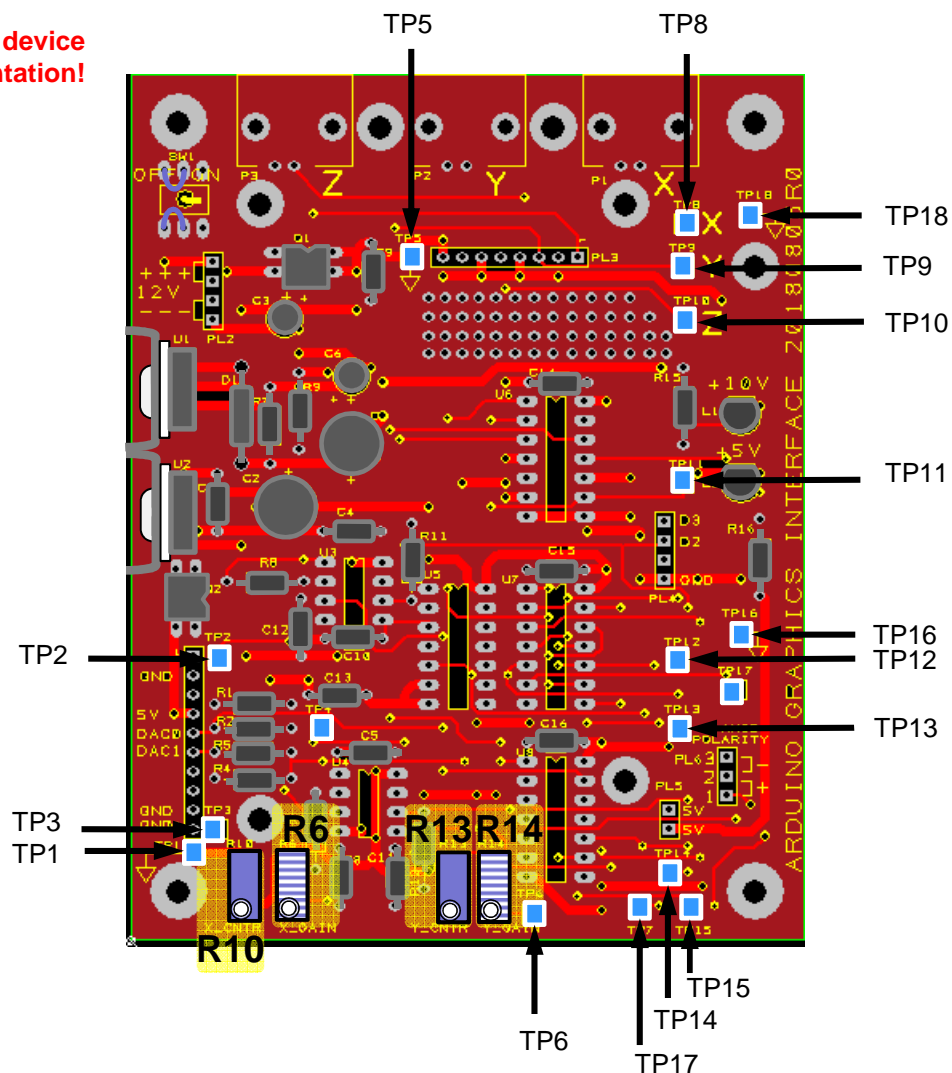
←Note device orientation!

TP1	1	GROUND, OPTIONAL
TP10	1	OPTIONAL
TP11	1	OPTIONAL
TP12	1	OPTIONAL
TP13	1	OPTIONAL
TP14	1	OPTIONAL
TP15	1	OPTIONAL
TP16	1	GROUND, OPTIONAL
TP17	1	OPTIONAL
TP18	1	GROUND, OPTIONAL
TP2	1	OPTIONAL
TP3	1	OPTIONAL
TP4	1	OPTIONAL
TP5	1	GROUND, OPTIONAL
TP6	1	OPTIONAL
TP7	1	OPTIONAL
TP8	1	OPTIONAL
TP9	1	OPTIONAL

Note: Installation of Test Point (TP) pins is OPTIONAL. TP pins may be omitted and scope probes touched to TP hole as needed.

Alternately, TP pins may be made from snap apart male-headers or short pieces of insulated wire protruding up from board.

TOP SIDE VIEW



Load Parts: Headers, Connectors, ICs

Ref Name	Qty	Value
P1	1	Can use Chassis Mnt BNC
P2	1	Can use Chassis Mnt BNC
P3	1	Can use Chassis Mnt BNC

ALTERNATE FOR P1-P3: If using Chassis-mount BNC connectors, construct a bracket for the BNC connectors to mount through. Then, mount the bracket to the PCB using holes provided and connector to PL3 or X-Y-Z connector pads appropriately.

PL1	1	10 PIN FEMALE HDR
PL2	1	4 PIN MALE HDR
PL4	1	4 PIN MALE HDR
PL5	1	2 PIN FEMALE HDR
PL6	1	3 PIN MALE HDR

PL3	1	8 PIN MALE - OPTIONAL
-----	---	-----------------------

→ **PL3** is optional and is only used when using off-board chassis-mounted BNC connectors.

IC SOCKETS (IC sockets is Highly Recommended!)

Install 8-Pin Sockets for U3 & U4.

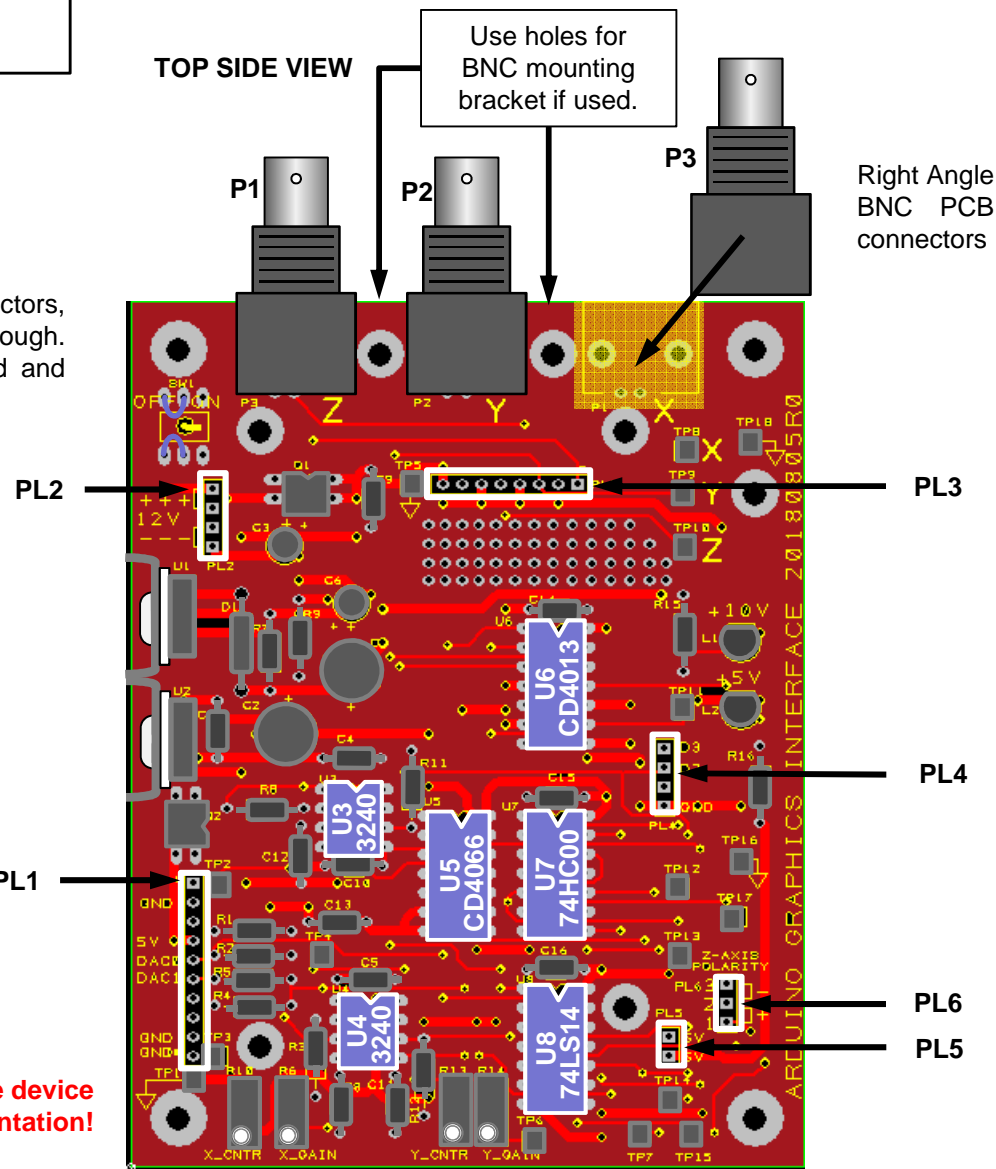
Install 14-Pin sockets for U5, U6, U7, and U8.

U3	1	CA3240	2	Install 8 Pin Socket	⏏
U4	1	CA3240			

← Note device orientation!

U5	1	CD4066			
U6	1	C4013BE	4	Install 14 Pin Socket	⏏
U7	1	74HC00			
U8	1	74LS14			

← Note device orientation!





Power Supply Checks & IC Installation

VERIFY POWER SUPPLY

CAUTION: BEFORE INSTALLING U3-U8, CHECK POWER SUPPLY!

1. With AGI board DISCONNECTED FROM Arduino DUE, apply power +12V to AGI BOARD via PL2.
 - a) OBSERVE < 25 MA current draw from +12 volt supply.
 - b) OBSERVE LED L1 & L2 are illuminated.
1. With a voltmeter, CONFIRM ANALOG VOLTAGE of 9.7-10.0 VDC is present at PIN 8 of U3 and U4.
2. With a voltmeter, CONFIRM 4.9-5.1VDC is present at PIN 14 of U5, U6, U7, U8.
3. Confirm +5V power is present at both pins of PL5.
4. Remove power from AGI & install U3-U8 per table below.

INSTALL ICs INTO SOCKETS

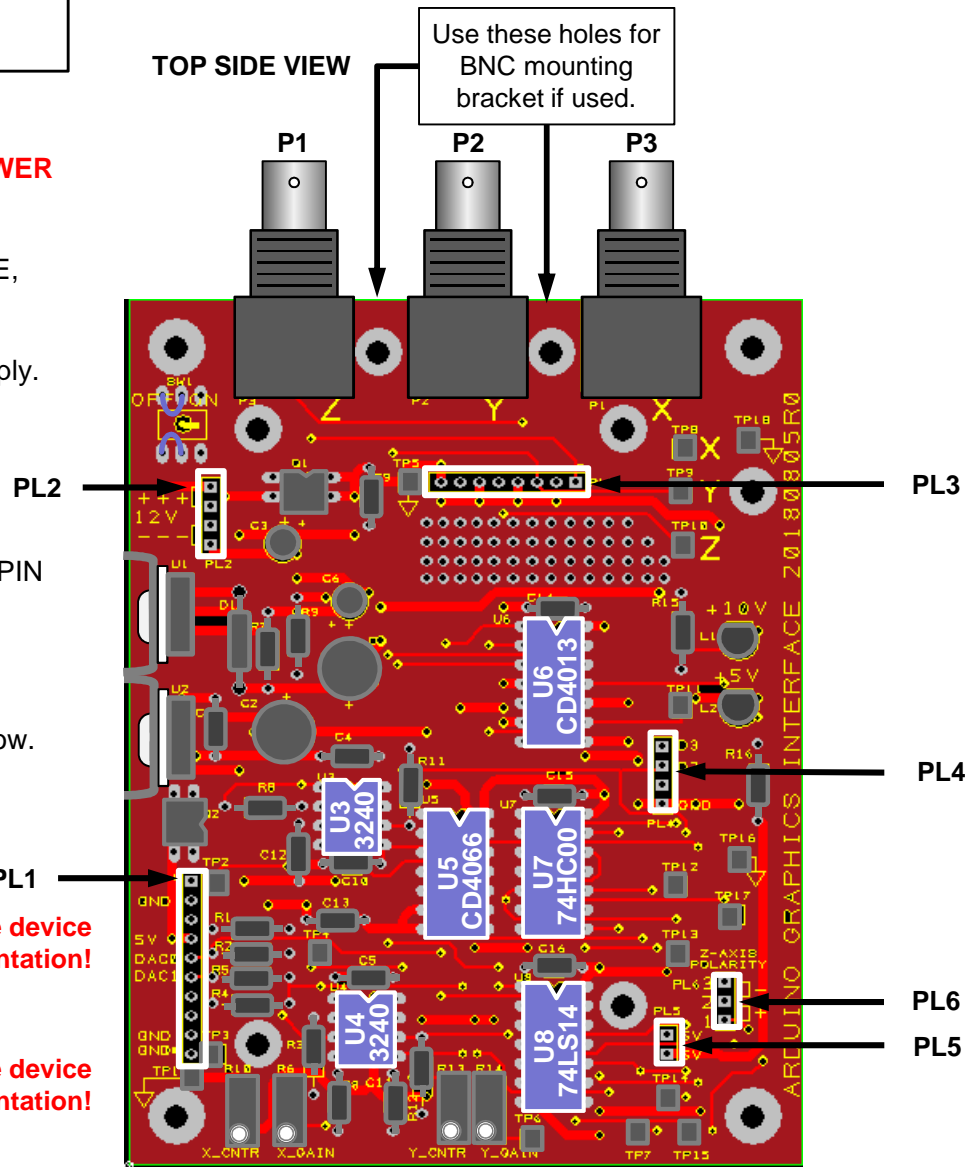
Ref Name	Qty	Value	
U3	1	CA3240	Install IC into 8 Pin Socket 
U4	1	CA3240	
U5	1	CD4066	Install IC into 14 Pin Socket 
U6	1	C4013BE	
U7	1	74HC00	
U8	1	74LS14	

←Note device orientation!

←Note device orientation!

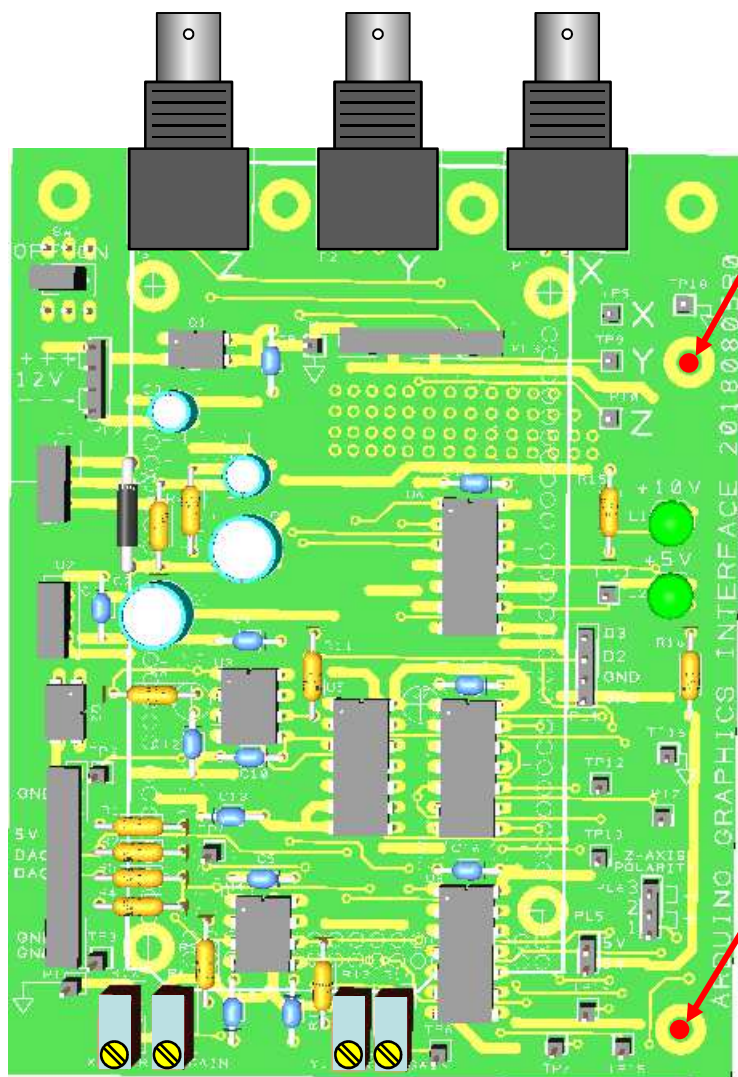
5. Apply +12V power to AGI through PL2 once again and observe proper +9.75 an 5 V levels and total current draw from 12 V supply to be less than 200 MA with DUE board attached

TOP SIDE VIEW

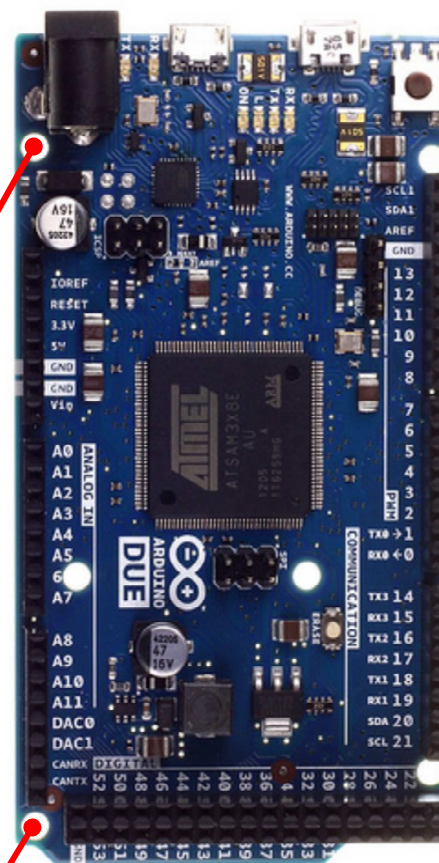


Test Mode Mounting, DUE to AGI PCB

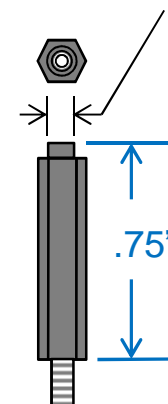
AGI PCB



ARDUINO DUE BOARD



Note: If using metal standoffs, it may be necessary to turn down a region at the top of each spacer so that metal of spacer does not short out pads on DUE!

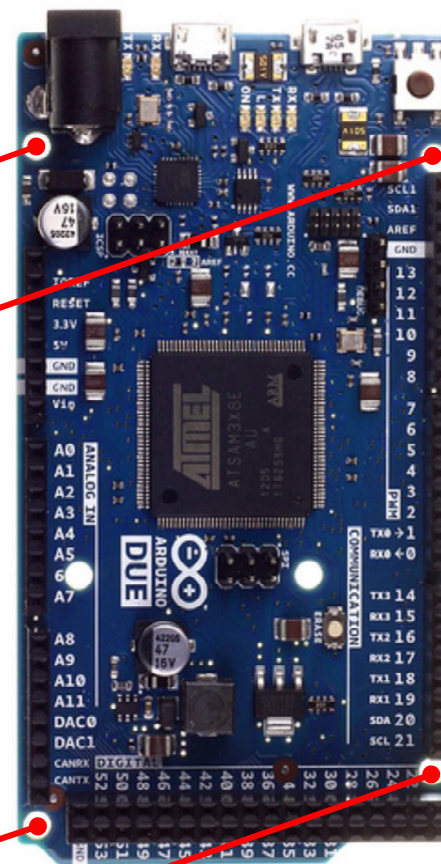
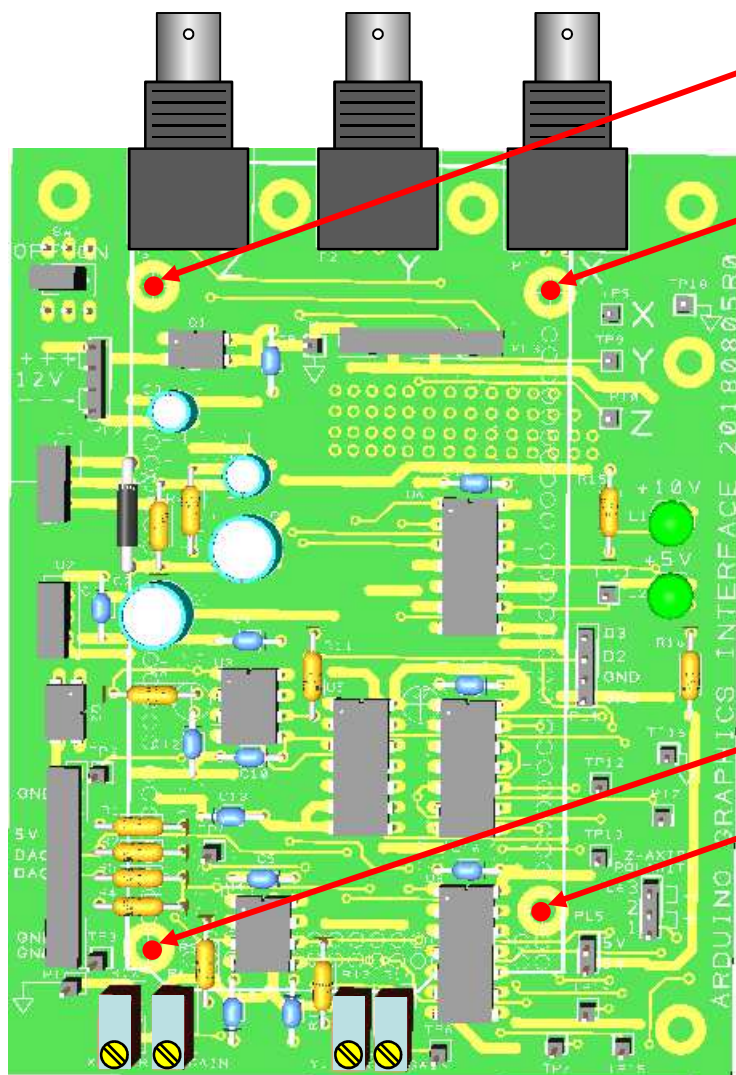


FOR TEST AND TROUBLE SHOOTING
Using 4-40 Standoff Spacers, Arduino DUE can be mounted to TOP RIGHT SIDE of AGI PCB in a *temporary fashion* so as to provide that full “scope-probe” test access to the AGI circuitry.

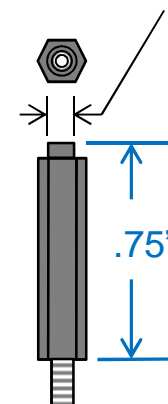
Final Mounting of DUE to AGI PCB

ARDUINO DUE BOARD

AGI PCB

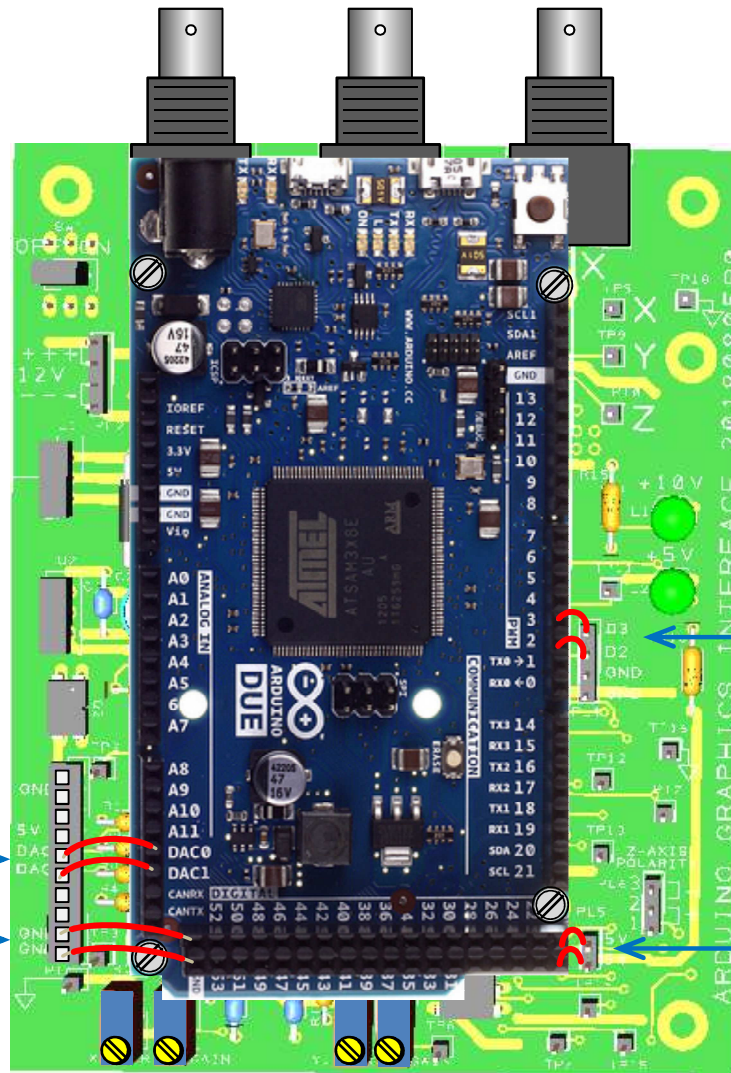


Note: If using metal standoffs, it may be necessary to turn down a region at the top of each spacer so that metal of spacer does not short out pads on DUE!



Using 4-40 Standoff Spacers, Arduino DUE can be mounted to TOP of AGI PCB. Additional Arduino Shields can then be installed onto DUE as needed.

Wiring AGI To DUE



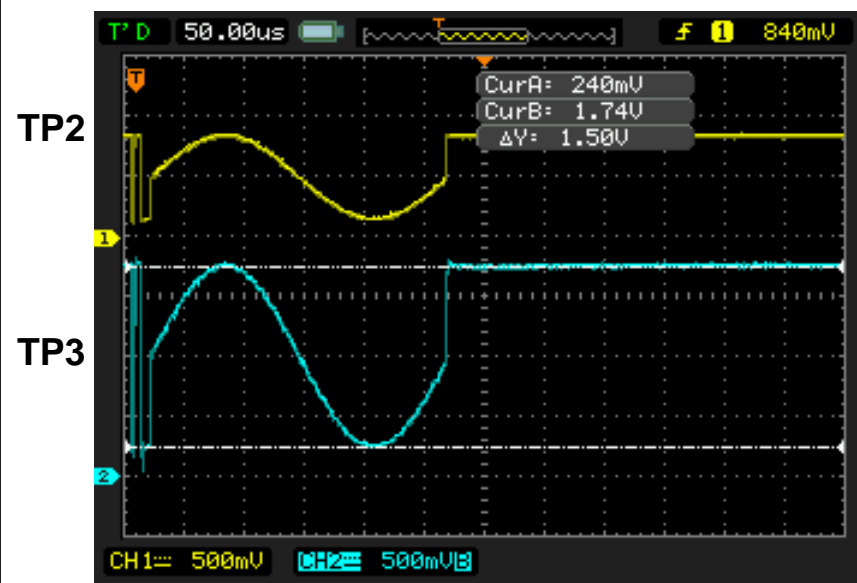
1) Connect DAC0 & DAC1 wires between AGI and DUE boards as shown.

2) Connect 2 GROUND wires between AGI and DUE boards as shown.

3) Connect D2 and D3 wires between AGI and DUE boards as shown.

4) Connect 2 +5V wires between AGI and DUE boards as shown.

X-Axis Gain and Offset Adjust



X-Gain and Offset Adjustment

1. Interconnect AGI to Arduino DUE and apply power to board.
2. Using Arduino IDE, Load and start CRT_SCOPE. Open a Serial Port (Baud=115200, NONE).
3. Select Option 7; This outputs a sine-wave segment on DAC0 and DAC1.
4. Connect an oscilloscope to TP2 and TP3. Trigger on TP2 as shown.
5. Observe approx. .7 V P-P signal on TP2 (DAC0 INPUT).
6. Adjust X_GAIN (R6) and X_CNTR (R10) pots until TP3 (X-Axis Buffer) displays approx. 1.5V P-P with Vmin .25-.50V above ground.
7. Connect & Place Scope in XY mode and final adjust pot in concert with scope gain and positions controls for proper XY display of a circle.

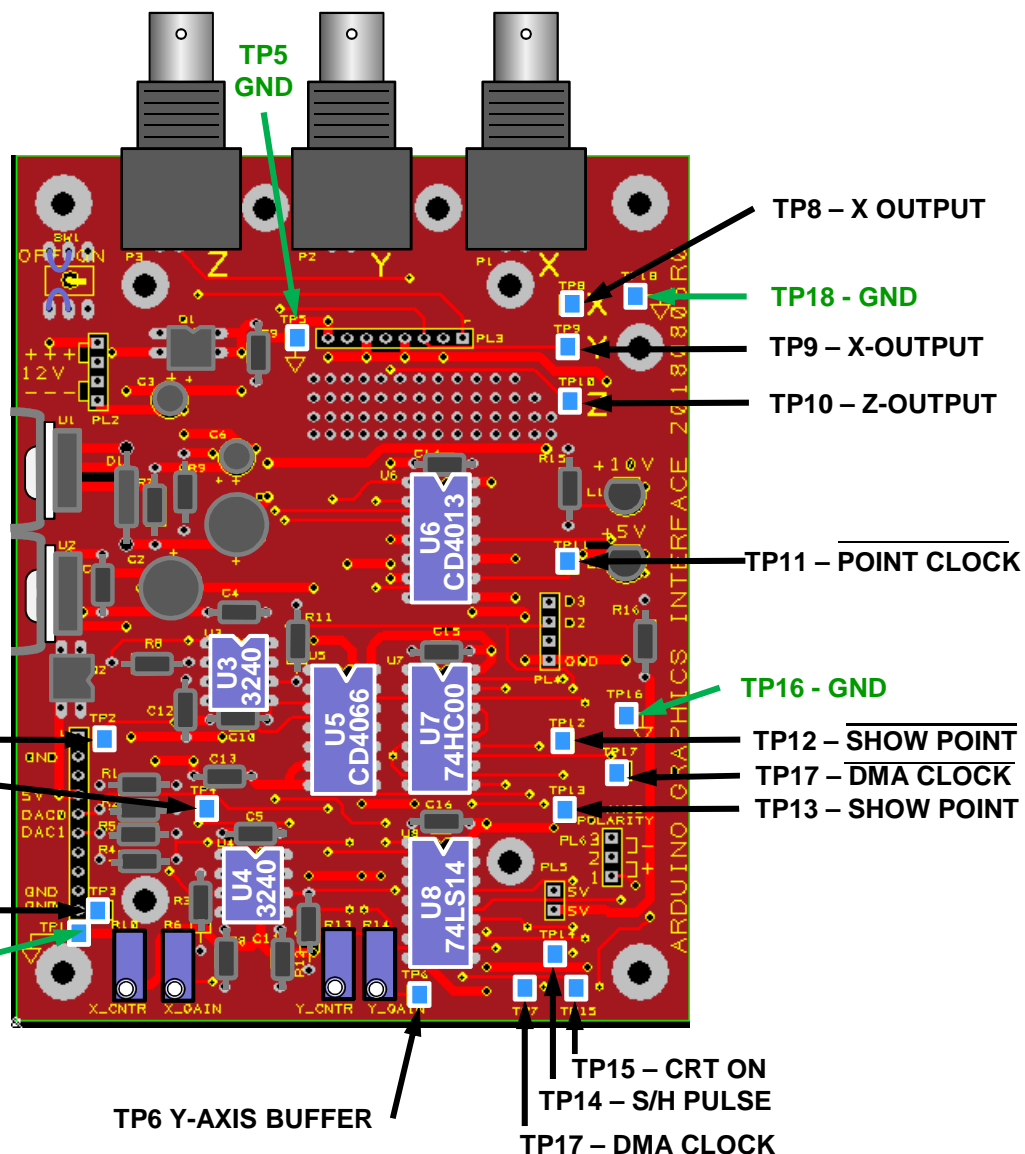
TP2 – DAC0 INPUT

TP4 – DAC1 INPUT

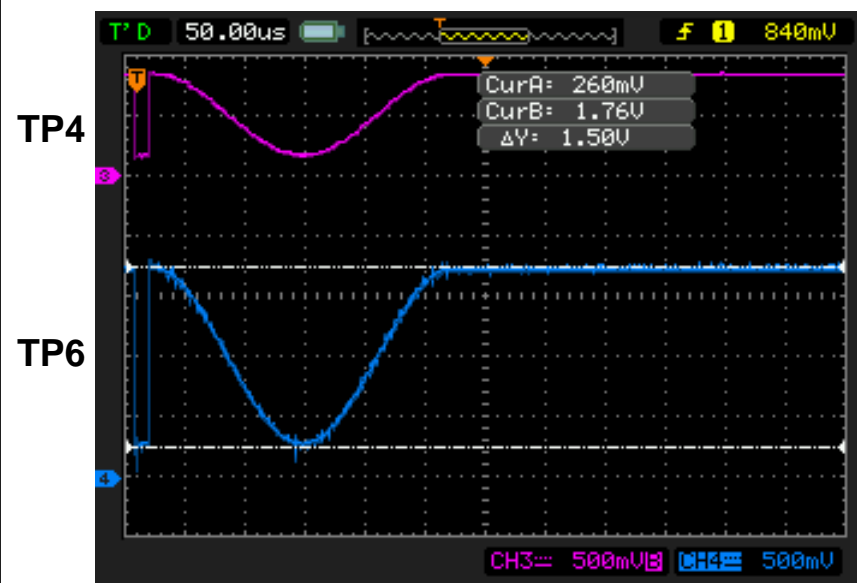
TP3 X-AXIS BUFFER

TP1 - GND

TOP SIDE VIEW



Y-Axis Gain and Offset Adjust



Y-Gain and Offset Adjustment

1. Interconnect AGI to Arduino DUE and apply power to board.
2. Using Arduino IDE, Load and start CRT_SCOPE. Open a Serial Port (Baud=115200, NONE).
3. Select Option 7; This output a sine-wave segment on DAC0 and DAC1.
4. Connect an oscilloscope to TP4 and TP6. Trigger on TP4 as shown.
5. Observe approx. .7 V P-P signal on TP4 (DAC1 INPUT).
6. Adjust Y_GAIN (R11) and Y_CNTR (R13) pots until TP6 (Y-Axis Buffer) displays approx. 1.5V P-P with Vmin .25-.50V above ground.
7. Connect & Place Scope in XY mode and final adjust pot in concert with scope gain and positions controls for proper XY display of a circle.

TP2 – DAC0 INPUT

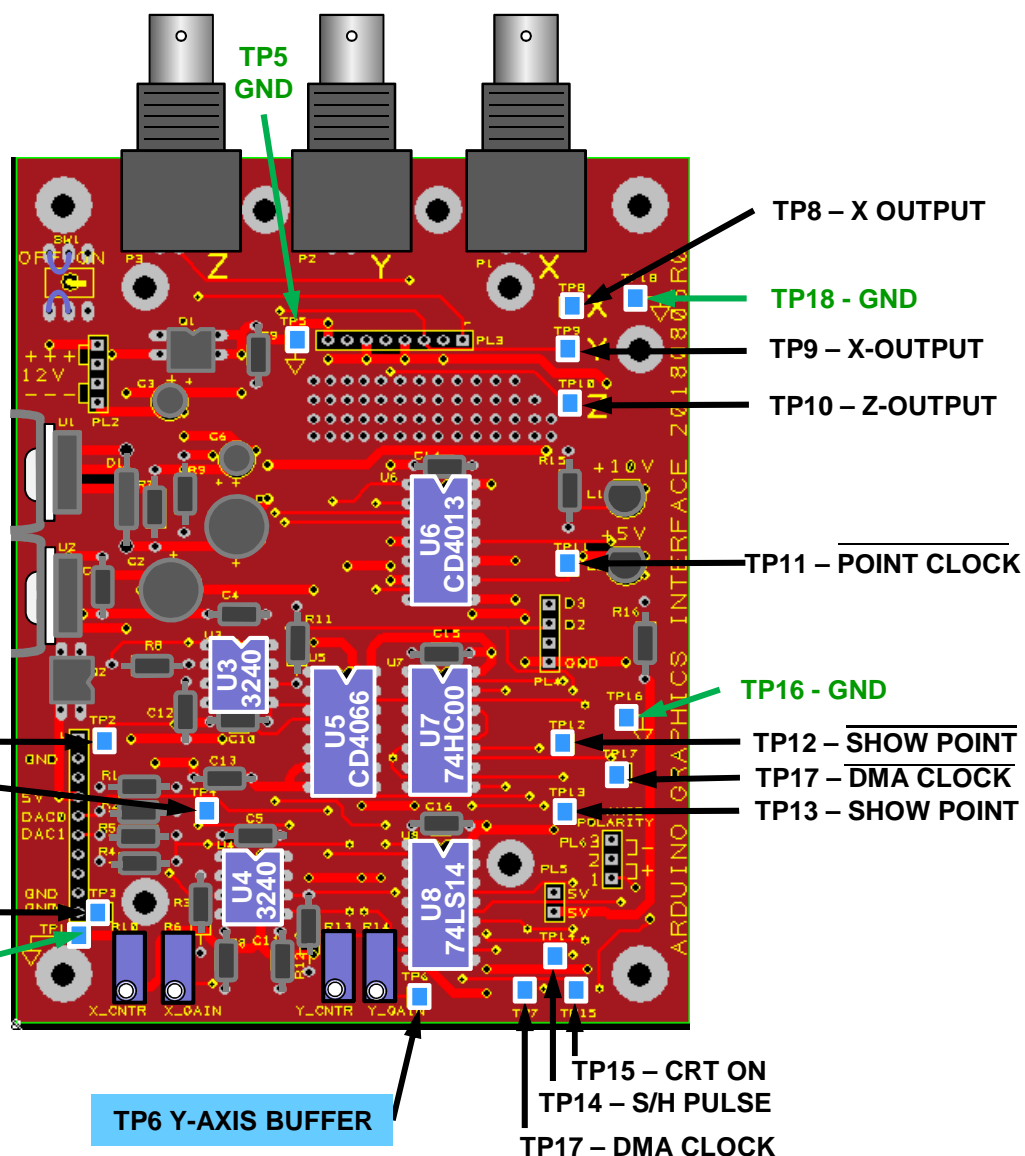
TP4 – DAC1 INPUT

TP3 X-AXIS BUFFER

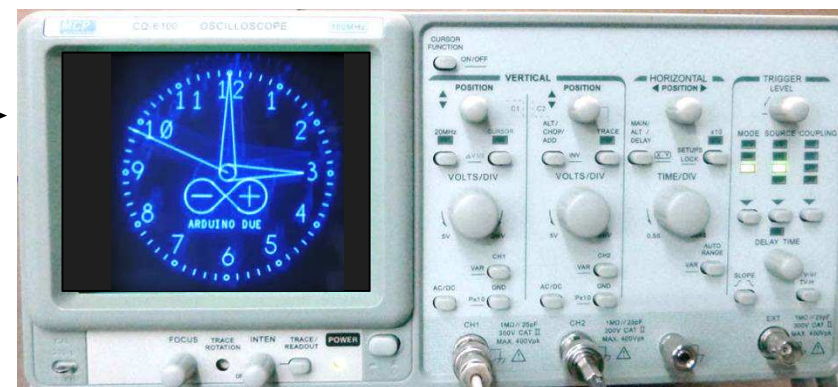
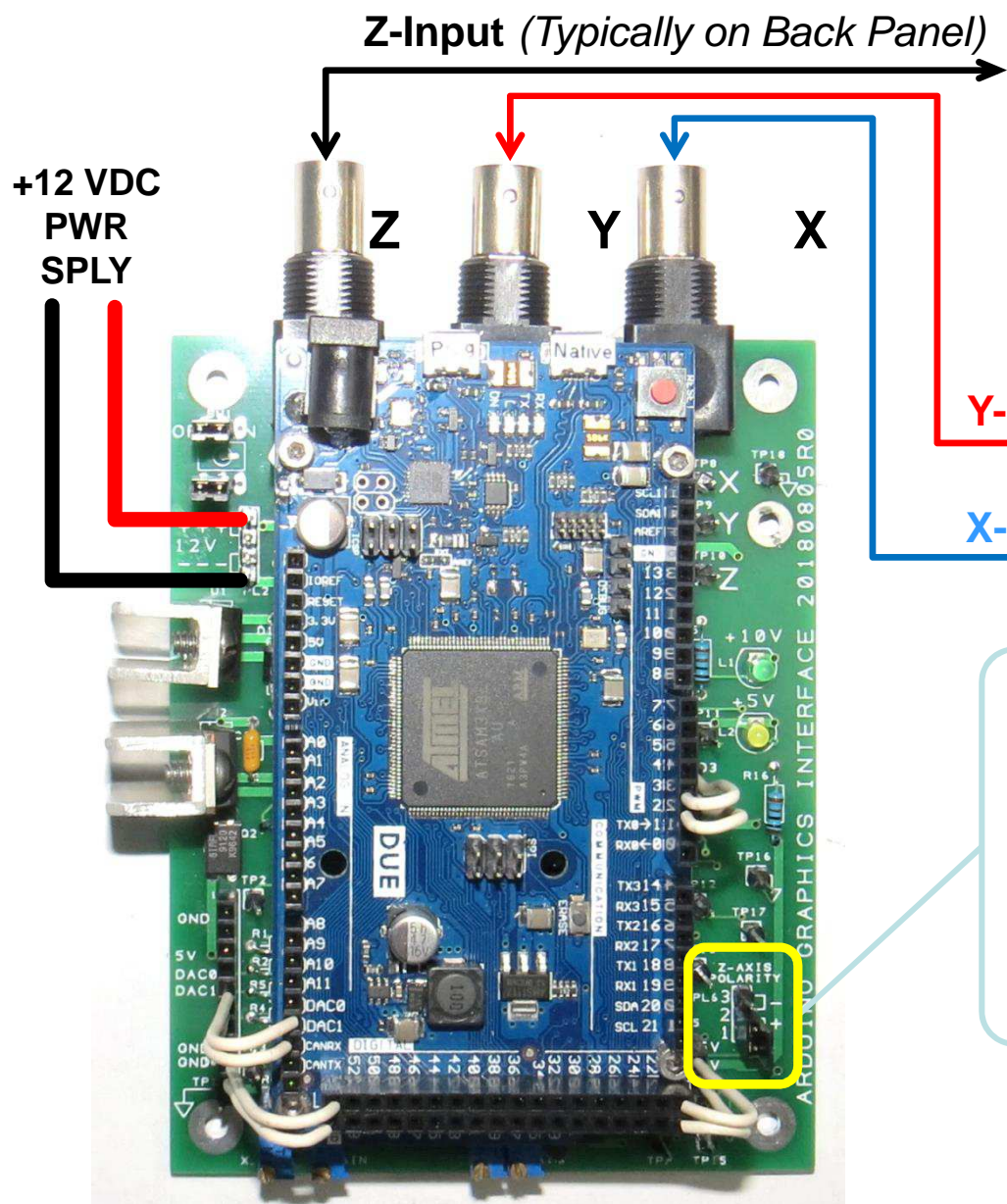
TP1 - GND

TP6 Y-AXIS BUFFER

TOP SIDE VIEW



Blanking Select & Wiring AGI To Scope



Y-Input (Typically CH 2)

X-Input (Typically CH 1)

PL6 JUMPER SETTINGS

- 3 ☐ **NEGATIVE Z-AXIS LOGIC**
Jumper position 2-3 for
Logic 0 = UNBLANK
- 2 ☐ **POSITIVE Z-AXIS LOGIC**
Jumper position 1-2 for
Logic 1 = UNBLANK

Test Pattern Descriptions

===== CRT_SCOPE_Ver_20.55 =====

? = Show this HELP Screen

---- Hardware setup and diagnostics ----

7 = Analog Signal Scope Pattern for Gain & Center Adj.

C = Incr DMA Clock Freq by 50 Khz

c = Decr DMA Clock Freq by 50 Khz

F = Incr Front-Porch blankCount by 1

f = Decr Front-Porch blankCount by 1

B = Incr Back-Porch blankCount by 1

b = Decr Back-Porch blankCount by 1

2 = Display Centering Pattern

v = Peak-to-Peak Vertical Sq-Wv Test Pattern

h = Peak-to-Peak Horizontal Sq-Wv Test Pattern

d = Peak-to-Peak Dots_in_the_Corners Test Pattern

---- Test plots for TEXT routines

i = Decr TEXT intensity for subsequent plots

I = Incr TEXT intensity for subsequent plots

0 = Print Numbers Test (Random Number)

1 = Print Numbers Test with some underlined (Rand Num)

s = plotChar Test #1

S = plotChar Test #2

w = Wakeup from Screen-save timeout

---- Test plots for GRAPHICS routines ----

+ = Incr Graphics Intensity for subsequent plots'

- = Decr Graphics Intensity for subsequent plots

3 = Display Random Rectangles, Circles, & Ellipses

4 = Simulated Graph Plot

5 = Display Random Ellipse

6 = Display a fixed Ellipse

8 = Demo Circle arc segments from 0 to 7

9 = Demo Ellipse arc segments from 0 to 7

---- Simulated Application Screens ----

l = Plot an animated Arduino Logo

D = Show AGI Coordinate System Plot

t = TIME - A Simulated Clock Display

* = Toggle 'SimClock' second-hand On-Off

p = Pong Simulation

→ This option will load a circular pattern into the XY_List buffer that will output a full-scale partial sin wave pattern out on the X and Y output ports. This can be used to set the gain and centering POTS on the AGI as well as scope gain and centering controls as shown on page 20 & 21.

→ Use these options to change the DMA_CLOCK frequency while observing the effects on plot quality on your scope.

→ Use these options to vary the duration and timing of the FRONT and BACK porch BLANKING SIGNAL.

→ This sends plots a full size circle inside of a full size square and can also be used to set scope gain and centering controls

→ Use this pattern plots to observe accuracy and/or artifacts when driving scope with FULL SCALE square wave pattern. Try varying the DMA_CLOCK (Option: c/C) while viewing these patterns.

THIS DOCUMENT CONTAINS PROJECT
SPECIFIC DOCUMENTATION

Made by: E. Andrews Date: 8-17-2017

First Made For

AGI: Arduino Graphics Interface

Filename

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Revision

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Page

23

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